iQpump 7 AC Drive (Software 0034) **Simplex Quick Start Procedure**

Step

UL File

The following procedure is a supplement to other documentation supplied with this equipment and will guide the user in properly wiring the iQpump and motor. It will also show the user how to configure the iQpump for a simplex pump

Danger:

application.

Improper wiring can and will cause bodily harm as well as damage to the equipment.

When installing the system, be sure to follow good wiring practices and all applicable codes. Ensure that the mounting of the various components are secure and that the environment. such as extreme dampness, poor ventilation, etc. will not cause system degradation.

Please read this cheat sheet and other documentation provided with the iQpump thoroughly before attempting any installation.

1 2 and Mounting To make sure you received the correct model, it is essential to verify the iQpump nameplate with your order and make sure the iQpump has the correct rating so it can be used with your motor. Please check the nameplate information as shown in the example below. Drive Mode Number MODEL: CIMR-P7U2011 SPEC: 20111A-U8901074 Input Powe Rating • INPUT: AC3PH 200-240V 50/60Hz 53A •OUTPUT: AC3PH 0-240V 0-120Hz 46.2A 18kVA Output Powe Rating O/N: Veigh MASS: 7.0kg PRG: 0034 S/N: 1W06Z712345000²

IP20

iQpump Model Identification

- Check that the available power will meet the input power
- requirements Ensure that the output power from the iQpump is

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- compatible with the pump motor requirements. In the case of systems with more than one iQpump, follow
- the above procedure for each iQpump and pump motor.

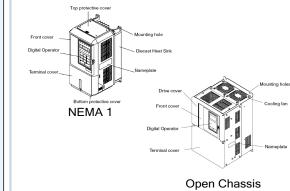
Mounting the iQpump

The mounting of the iQpump is extremely important regarding environment and accessibility. Depending on your system, there are various models available and the mounting dimensions (footprint) may be different. Because the mounting procedure is fairly extensive, it is beyond the scope of this document; the user is referred to the iQpump User Manual (Document No. TM.iQp.06) received with the iQpump. Section 1 Physical Installation. Match the model that you received and follow the procedure described in the manual to ensure a safe and functional installation. In cases where the system has more than one iQpump, refer to the proper clearances required for adequate ventilation. Please pay particular attention to:

- The clearances to be maintained around the enclosure for adequate ventilation
- The environmental specifications such as avoiding excessive dampness, extreme temperatures, chemical exposure, corrosive areas, etc. to avoid damage to the equipment and to maintain safety.

Removing and Attaching the Terminal Cover

Improper removal of the iQpump terminal cover as well as front cover can cause extensive damage to the iQpump. To avoid damage to these items, please pay particular attention to the iQpump User Manual, Document No. TM.iQp.06, Section 1.8, Removing and Attaching the Terminal Cover.





Step

Connect Pump Motor and Line Power

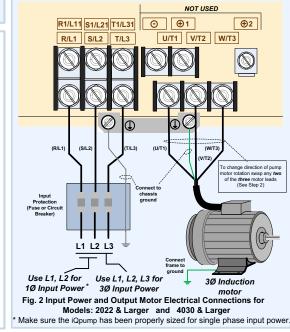
Fig.1 & 2 below show the electrical connections for the input power and motor terminals for various iQpump models. Select the proper diagram for the model you are installing (see Step 1). WITH POWER OFF make the appropriate connections.

Make sure to follow good wiring practices and all applicable codes. Ensure that the equipment is grounded properly as shown.

DANGER; LETHAL VOLTAGES ARE PRESENT- Before applying power to the iQpump, ensure that the terminal cover is fastened and all wiring connections are secure. After the power has been turned OFF, wait at least five minutes until the charge indicator extinguishes completely before touching any wiring, circuit boards or components.

WARNING DO NOT CONNECT ANY OF THE FOLLOWING TERMINALS TO EARTH GROUND $\mathbf{X} \mathbf{X} \mathbf{X} \mathbf{X} \mathbf{X} \mathbf{X} \mathbf{X}$

NOT USED (R/L1) chassis ground pump motor rotation swap any two of the (See Sten 2 L1 L2 L3 Connect rame to ground Use L1, L2 for Use L1, L2, L3 for 3Ø Induction 3Ø Input Power 10 Input Power Fig. 1 Input Power and Output Motor Electrical Connections for Models: 20P4 to 2018 and 40P4 to 4018



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Step

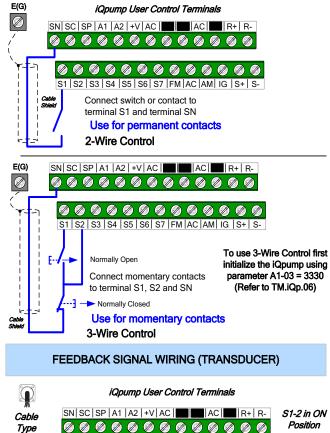
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Control Wiring

This step shows how to connect control wiring and feedback signal to the iQpump. Before making any control connections, MAKE SURE POWER TO THE iQpump IS TURNED OFF! Next remove the terminal cover to gain access to the control terminals. (Step 1.)

SELECT START / STOP CONTROL METHOD

The iQpump is **DEFAULT SETUP TO START/STOP FROM THE** KEYPAD (digital operator). If this is the preferred start/stop method, then continue to the feedback signal connection section. Please refer to the wiring diagram below to start/stop the iQpump using an external switch or contact.



Cable Shield

Blue or Black

E(G) 🔗 🔗 🖉

Black: Output

4 - 20mA (2)

Black or White Output -

S1 | S2 | S3 | S4

For use with 3-Wire, 0 - 10V Transducer

depending on feedback device used.

Please consult feedback device manual.

S1 S2 S3 S4

 \oslash

DIN

Туре

E(G)

 \oslash

0 - 10V (3)

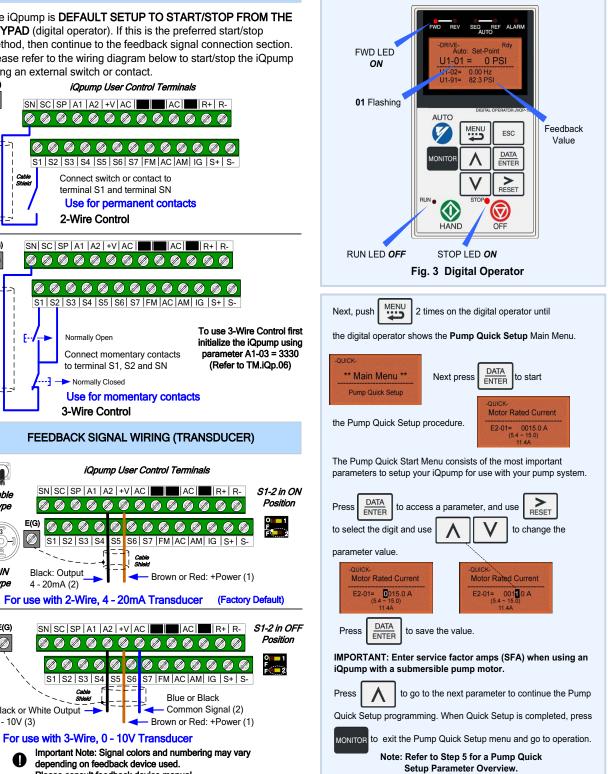
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In this step, the iQpump is setup for a simplex pump application using the Pump Quick Setup menu. Apply power to the iQpump after all the electrical connections have been made and the terminal cover has been re-attached. At this point DO NOT RUN THE MOTOR the digital operator should be reading as shown below in Fig. 3.

Pump Quick Setup

Step

4



Step 5



iQpump Quick Setup Parameter Overview (Simplex)

Paran	neter Value	Description	Reference	Comments	1 TRANSDUCER / FEEDBACK DEVICE SCALING P1-03 = 0 0 0 Feedback Scaling
E2-	01 Drive Size Dependent	Motor Rated Current	Set to the motor nameplate full load amps.	For submersible motors use service factor amps (SFA).	Examples: 0 - 1000, no decimals, P1-03 = 1000 Feedback Maximum 0 - 300.0, one decimal, P1-03 = 10300
E2-	04 2	Number of Motor Poles	Number of motor poles is used to show the correct motor RPM on the display Enter '4' for an 1800 RPM motor and '2' for a 3600 RPM motor.	Confirm number of poles 2 Pole Motor = 3600 RPM 4 Pole Motor = 1800 RPM 6 Pole Motor = 1200 RPM 8 Pole Motor = 900 RPM	Decimal Point Position 2 START LEVEL Example: Absolute Level (Positive Start Level)
P1-	03 145	Feedback Device Scaling	System Scaling: Enter feedback device maximum: Example: Enter 200 for pressure transducer with a maximum of 200 PSI at 20mA.	Confirm feedback device scaling. (See Illustration 1)	200 PSI Start Level Delay (P1-05) (Example 5.0 sec.) (4 - 20 mA)
d1-	01 0	Set-Point 1	Set System Set-Point	Set to system pressure	150 System Set-Point (Example 150 PSI)
P1-	04 0.0 PSI	Start Level	When the iQpump is turned On and the feedback signal level (transducer) falls below this level, the pump system will start after the time specified in P1-05 (default 1 sec). Programming the Start Level as an Absolute Value Start Level has to programmed to a positive value in order for the Start Level to be an absolute value. Example: Start Level P1-04 set to 50 PSI and delay time P1-05 set to 5 sec . Pump system will start when the pressure drops below 50 PSI for 5 sec. Programming the Start Level as a Delta Level from the System Set-Point Start Level has to programmed to a negative value in order for the Start Level to be a delta value from the set-point. Example: Start Level P1-04 set to – 10 PSI with a system set-point of 50 PSI and a delay time P1-05 set to 5 sec . MDV Start Level Rdy Use Ndy Use Ndy Use Ndy to change the sign.	It is mandatory to program the Start Level in order to use the sleep function. (See Illustration 2 and 3)	Start Level P1-04 (Absolute) (Example 100 PSI) Feedback Scaling (P1-03) (Example 200 PSI) Example: Delta Level (Negative Start Level) Note: When System Set-point is changed, the start level is automatically adjusted. Start Level Delay (P1-05) (Example 5.0 sec.) Start Level Delay (P1-05) (Example 5.0 sec.) Start Level Delay (P1-05) (Example 5.0 sec.) Start Level P1-04 (Delta) (Example 150 PSI) System Set-Point (Example 150 PSI) Start Level P1-04 (Delta) (Example 200 PSI) Start Level P1-04 (Delta) (Example 5.0 sec.) Output Frequency Step Delay Time (P2-03) Frequency Step Delay Time (P2-03) Step Delay Time (P2-03) Frequency Step Delay Time (P2-03) Step Delay Time (P2-03) Step Delay Time (P2-03) Step Delay Time (P2-03) <
P1-	06 40.0 Hz	Minimum Pump Frequency	Minimum speed (Hz) the pump motor has to operate at. Example: Base pump motor speed is 3600 RPM, minimum speed is 2400 RPM. Set minimum pump frequency to 40.0 Hz. (2400 ÷ 3600 x 60 Hz = 40 Hz)	Minimum pump frequency should be set to a value where the pump enters a no-flow condition.	(pump motor speed) Minimum Speed P1-06 (Example 40.0 Hz)
P4-	10 0 Disabled	Auto Mode Operator Run Power Down Storage	Stores the run status in the Auto mode when operating from digital operator (b1-02=0). 0: Disabled 1: Enabled	Recommended for use when Start/Stop command is from keypad. (See Illustration 6)	0 Pump Pupping Co to Sloop WAIT FOR PRESSURE TO FALL BELOW
P5-	04 1 Enabled	Hand Key Enable / Disable	Enables or disables the Hand Key on the digital operator. 0: Disabled 1: Enabled	Hand Key on keypad. (See Illustration 4)	Time ->

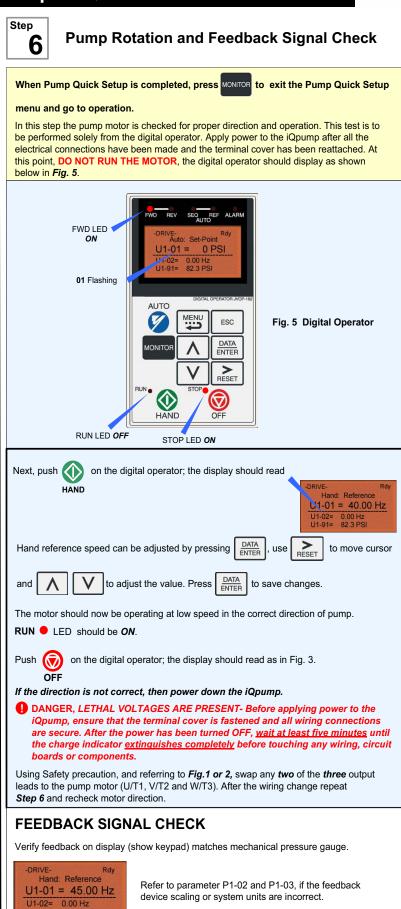


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iQpump Factory Defaults Overview (only adjust settings based on your application)

Parameter	Value	Description	Reference	Comments	4 HAND MODE OPERATION
b5-03	3.0 sec.	PI Integral Time	Decrease integral time to make iQpump more responsive.	<i>Caution:</i> can cause instability if value is too low.	Hand Speed from the Keypad/Digital Operator (Default)Press the HAND KEY on the digital operator to run the system in Hand Mode.Hand Mode speed can be adjusted by pressing $DATA$ ENTER, use $RESET$ to move the cursor and M Mode the cursor and M <
b5-12	2 (Fault)	PI Feedback Reference Missing Detection Selection	 Select what to do when the feedback device (transducer) fails or gets disconnected. Disabled, continue running no message is displayed 1: Alarm, show warning on the keypad when the feedback device fails or is disconnected 2: Fault, stop pump system when the feedback fails or is disconnected 	NOTE : Disable parameter b5-12 if no transducer is installed.	UPRIVE- Hand: Reference. U1-01 = 040.00Hz Press (0.00-120.0.) '40.00Hz' DATA ENTER '0' Blinking Digital operator JVOP-162
b5-14	2.0 sec.	PI Feedback Loss Detection Time	Delay time before iQpump shows alarm or fault when feedback device has failed or is disconnected. Example: 2.0 sec., iQpump displays alarm or fault 2 sec. after the device has failed or is disconnected.		Hand Speed from Analog Input (0 – 10V) Set parameter P5-01 'Hand Mode Ref.' to '0' to adjust the hand mode reference from an external 0 – 10V signal connected to terminal A1 and AC. SNISC SP A1 A2 +V AC
C1-01	20.0 sec.	Acceleration Time 1	Time it takes to accelerate the pump motor from zero to maximum speed.	Adjusted depending on system	S1 S2 S3 S4 S5 S6 S7 FM AC AM IG S+ S- + - HAND V 0 - 10V
C1-02	10.0 sec.	Deceleration Time 1	Time it takes to decelerate the pump motor from maximum speed to zero.	penomance	Note: Hand Key can be disabled with parameter P5-04
L5-01	5	Number of Restart Attempts	Determines the number of times iQpump will perform an automatic restart on the faults listed in the comments column. iQpump System Protection Faults that can be setup to restart are Low Level Feedback, High Level Feedback, Transducer Loss, Not Maintaining Set-point, Loss of Prime, Pump Over Cycle. Refer to parameters P4-07 and P4-08. The number of restart attempts is set by L5-01.	 Overcurrent Ground Fault Output Phase Loss Input Phase Loss iQpump Overload 	5 THRUST BEARING - SUBMERSIBLE MOTORS (e.g. Franklin) Note: Thrust Bearing Function is Enabled by Default When using a submersible motor in combination with iQpump, it is recommended to use the Thrust Bearing function to prevent excess motor wear. To enable this function, enter the minimum motor frequency in parameter P4-05. Example: Minimum motor speed 1800 RPM, 1800 RPM ÷ 3600 RPM x 60.0 Hz = 30.0 Hz
L5-03	20 sec.	Maximum Restart Time After Fault	If the restart fails (or is not attempted due to a continuing fault condition) iQpump waits the Maximum Restart Time After Fault, before attempting another restart.	 Motor Overload Overtorque DC Bus Fuse Blown DC Bus Undervoltage DC Bus Overvoltage Overheat 	Cl-01 Acceleration Time C1-01
P1-06	40.0 Hz	Minimum Pump Frequency	Minimum speed (Hz) the pump motor has to operate at. Example: Base pump motor speed is 3600 RPM, minimum speed is 2400 RPM. Set minimum pump frequency to 40.0 Hz. (2400 ÷ 3600 x 60 Hz = 40 Hz)	P1-06 should be set to the level where the pump can produce the minimum pressure even at zero flow.	Thrust Bearing Auto/Hand Operation
P2-03	5 sec.	Sleep Delay Time	Time it takes before the pump system goes to sleep when the selected signal level (P2-01) falls below the specified sleep level (P2-02)	Adjust according to system requirements.	6 AUTO OPERATION – POWER DOWN STORAGE
P4-05	30.0 Hz	Thrust Bearing Frequency	Sets the frequency reference used when the thrust bearing function is active. A value of 0 disables this function.	Primarily used for submersible pumps. Program P4-05 = 0.0 Hz to disable function when iQpump is used with a centrifugal pump.	Allows iQpump to automatically start after power failure when operated from keypad / digital operator. This function is recommended for use when operating the iQpump in remote / unmanned areas.
P4-11	0.2 Min	Utility Start Delay	When utility power is restored and P4-10 is enabled (1), iQpump waits the time specified in P4-11 before auto operation becomes active.	Note: Only active when P4-10 is enabled (1) and operation (start/stop) is from the digital operator.	When the iQpump is powered down while running, an internal run command will automatically be initiated upon power-up.

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Step Auto Mode Operation

iQpump can be operated in automatic mode when the following actions have been performed.

- - · All parameters are programmed
 - Pump motor direction has been checked
 - Feedback signal has been checked

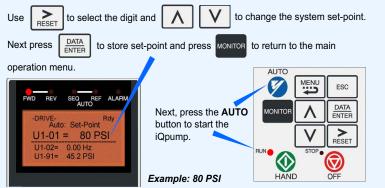
At this point, DO NOT RUN THE MOTOR, the digital operator should display as shown below in Fig. 6.



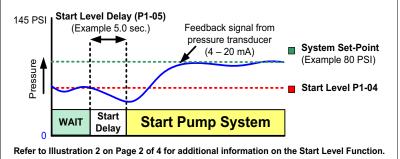
SET SYSTEM SET-POINT

Next, press to access or modify the system set-point that was entered using

parameter d1-01 System Set-point in the Pump Quick Setup Menu



iQpump automatically starts in Auto Mode when the feedback signal level falls below the programmed level in parameter P1-04 for the specified time in P1-05.



Sleep and Anti-No-Flow (ANF) Detection (P2-23, P2-24, P2-25)

NOTE: Before adjusting Anti-No-Flow operation ensure your system is regulating satisfactory while operating under normal running conditions.

If stable continue to Step 1 to verify no-flow/sleep operation. If unstable turn off the Anti-No-Flow function (P2-23 = 0.00%) and adjust the PI control parameters b5-02 and b5-03 to stabilize pump system. Refer to iQpump User Manual (Document No. TM.iQp.06) for additional information. Once the system is stable, re-enable the Anti-No-Flow function by setting P2-23 to 0.40% and continue to Step 1 to verify no-flow/sleep operation.

Step 1: Verify system holds pressure by creating a no-flow situation (e.g. close off discharge valve).

Step 2: Press OFF button on the digital operator, wait 1 min. until system stabilizes and verify system pressure feedback U1-91. If the pressure drops more than 3 PSI (U1-91) adjust P2-25 to the actual delta pressure drop plus 1 PSI.

Example: Set-point is 80 PSI, pressure feedback U1-91 shows 76 PSI, P2-25 should be 4 + 1 or 5 PSI. Note: This value should always be more than your start level (P1-04). If not, the system pressure is not holding and this needs to be corrected, or the pump system will continue to cycle on and off.

Step 3: Run system in normal automatic operation with flow. Next check monitor U1-99 "ANF Timer" and verify that the value is incrementing and resetting back to zero continuously. If the value holds at 10 sec. (P2-24) increase P2-24 "Anti-No-Flow Detection Time" by increments of 5 sec. Repeat Step 3 each time P2-24 is adjusted.

Step 4: Create a no-flow situation (e.g. close discharge valve) and monitor that U1-99 "ANF Timer" increments and holds at P2-24 time (value set in Step 3). Once the Anti-No-Flow timer expires the speed will reduce gradually until it reaches minimum pump speed (P1-06) where it will hold for 5 sec. (P2-03) before going to sleep.

Step 5: Run system in normal automatic operation and verify sleep and wake-up operation until system performs satisfactory.

TYPICAL DISPLAY MESSAGES





Displays when the iQpump is about to start. The feedback level has fallen below the Start Level (P1-04) and the start delay timer is active. Once the Start Level Delay Time (P1-05) expires the iQpump will start



P4-05

Displays when the iQpump is in "sleep" mode or when the iQpump is waiting for the feedback level to drop below the Start Level (P1-04)



The feedback level has risen above P1-09 level for the time specified in P1-10. High feedback fault is active in Hand Mode. Auto Mode, Pre-Charge and Thrust Mode when the iQpump is running

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Displays when "Thrust Bearing" mode is active. To enable, enter value in parameter

FEEDBACK SIGNAL LEVEL

U1-91= 82.3 PS